re:Invent

NOV. 28 - DEC. 2, 2022 | LAS VEGAS, NV

CMP401

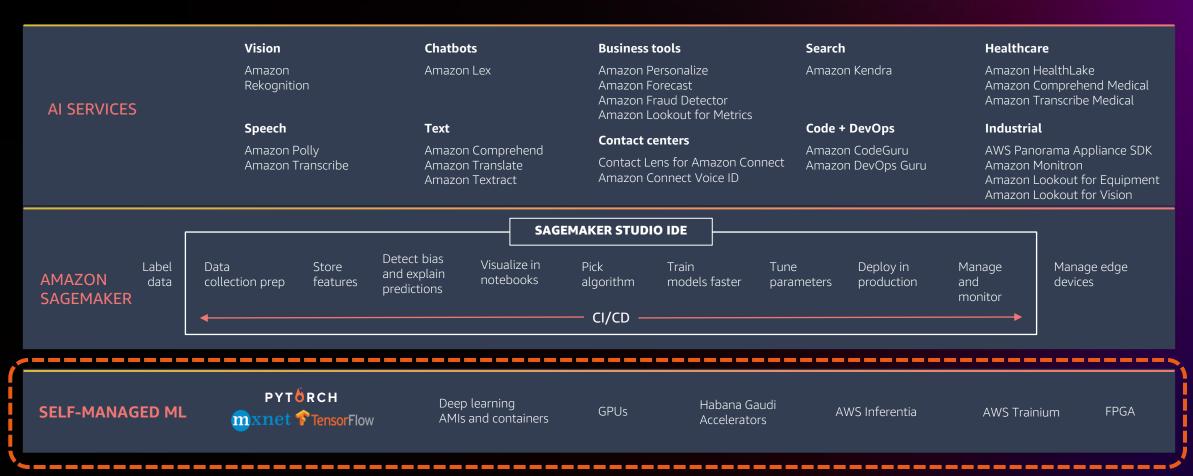
Scaling ML training and inference workloads on Amazon EC2 and PyTorch

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AWS



The AWS ML Stack

BROAD SET OF MACHINE LEARNING CAPABILITIES



ML Frameworks WWSO helps customers developing custom ML



What are we talking about today?

The scaling problem and where PyTorch FSDP comes in

What is FSDP exactly?

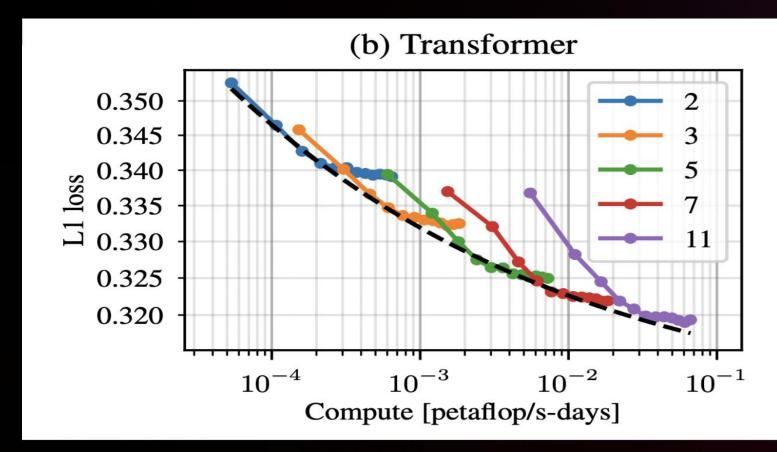
Code snippets

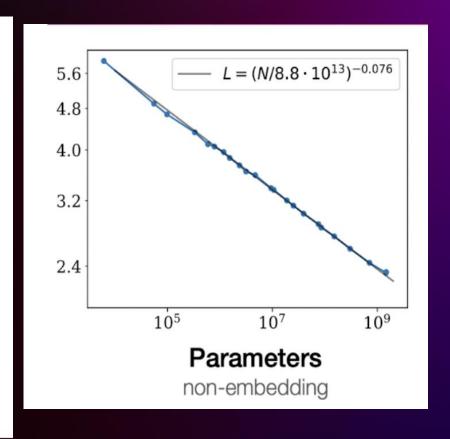
Details: Activation Checkpointing, Sharding Strategies

Additional new PyTorch features for extremely large models



Scaling problem: Strong payoff from increasing model size





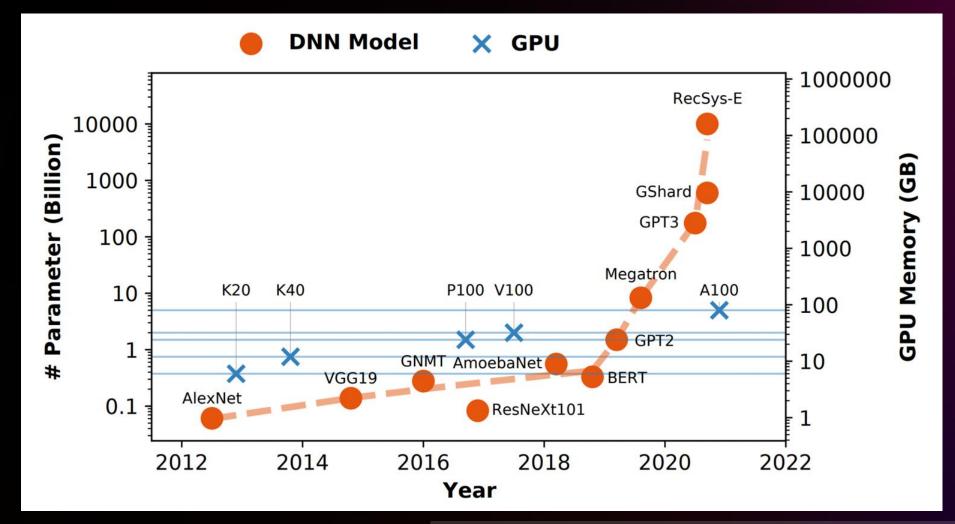
Performance improves smoothly as you increase model size, compute time and dataset size. (power law or power law + constant)

*OpenAI - Scaling Laws for Neural Language Models

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Scaling laws for Acoustic models

Thus, AI models have gone up 10,000x in size (but... GPU memory has only gone up ~10x)





FSDP (Fully Sharded Data Parallel)

Train a much larger model with same resources

Resource efficiency: Significantly reduce memory footprint on each GPU

Compute efficiency: Overlapping compute and communication

Ease of use: Lightweight config, just few knobs

Model	Number of layers	Hidden size	Attention heads	Model size, billions of parameters
GPT 175B	96	12288	96	175
GPT 1T	128	25600	160	1008

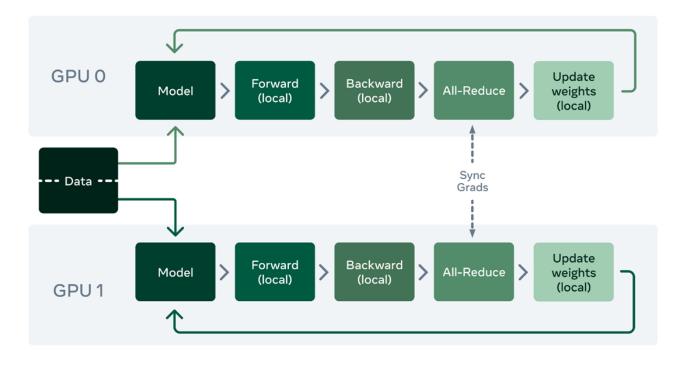


FSDP compared to DDP. DDP = sharding batch

Parallel = models are duplicated on multiple GPUs.

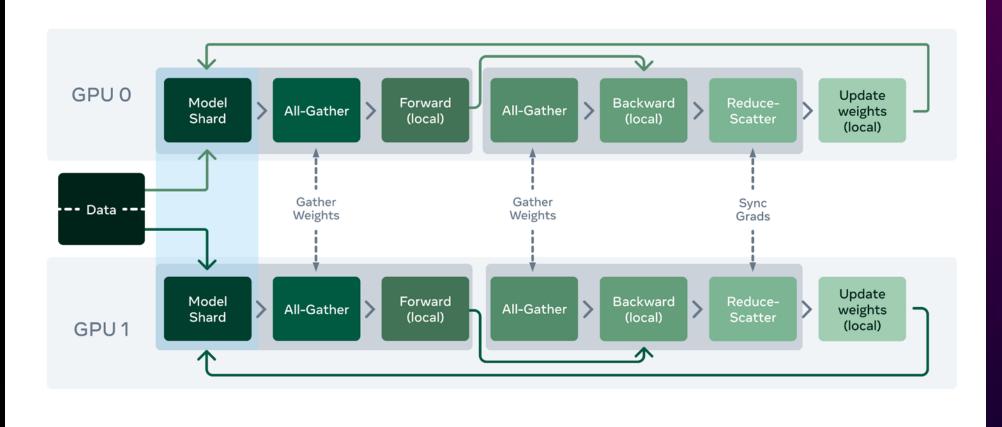
Data is sharded and submitted, each GPU processes.

Standard data parallel training

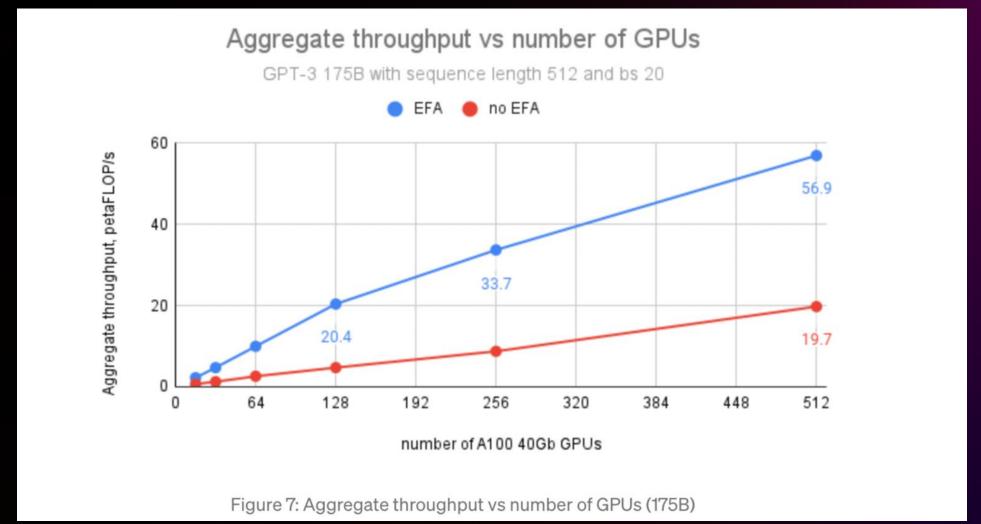


Fully Sharded Data Parallel (FSDP)

Fully sharded data parallel training



With sufficient inter-node communication speed, scaling with FSDP can be linear.





PyTorch FSDP Sharding Strategy Details:

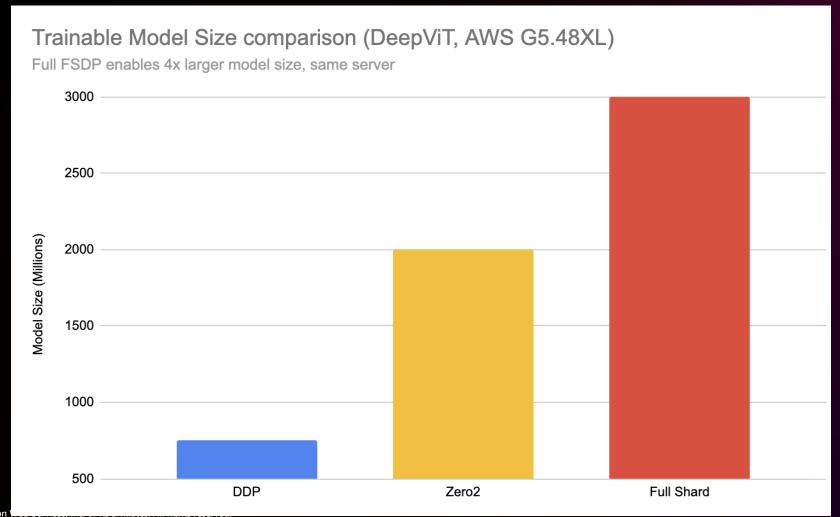
```
# import FSDP, including the class enum ShardingStrategy:
198
     from torch.distributed.fsdp import (
199
200
         FullyShardedDataParallel as FSDP,
201
         ShardingStrategy,
202
203
204
     # Three available sharding strategies - tradeoff memory size vs communication overhead:
205
     ShardingStrategy.FULL_SHARD # default! Model, optimizer and gradient are all sharded (communicated) ...
206
                                 # max model size support
207
     ShardingStrategy.SHARD_GRAD_OP # Zero2 mode - model parameters are not freed after forward pass,
208
                                 # reducing communication needs
     ShardingStrategy.NO_SHARD # DDP mode - each GPU keeps a full copy of the model, optimizer and gradients
209
210
                                # only grad synch needed
211
212
     # Future support:
213
     ShardingStrategy.HYBRID_SHARD #FSDP Full shard within each node, but No Shard (DDP) between each nodes.
214
215
     # To use - just pass in desired sharding at FSDP init:
216
     # ---- main FSDP init -----
         model = FSDP(
217
218
             model,
219
             auto_wrap_policy=my_auto_wrap_policy,
220
             mixed_precision=mp_policy,
221
             backward_prefetch=prefetch_policy,
222
             # sharding control
223
             sharding_strategy=ShardingStrategy.SHARD_GRAD_OP,  # Zero2 or DDP, or Full_Shard (FSDP default)
224
             device_id=torch.cuda.current_device(),
225
```

Fast network → full-shard

Slower network → experiment with Zero2 and DDP

Scaling benefits with FSDP - 4x larger models can be trained, same hardware with no other changes.

(Adding in Activation Checkpointing and CPU offloading can go 21x+)





Fine grained Mixed Precision control via Policies

```
20
     bfSixteen = MixedPrecision(
21
         # Parameter precision
22
         param_dtype=torch.bfloat16,
23
         # Gradient communication precision.
24
         reduce_dtype=torch.bfloat16,
25
         # Buffer precision.
26
         buffer_dtype=torch.bfloat16,
27
```



Fine grained Mixed Precision control via Policies

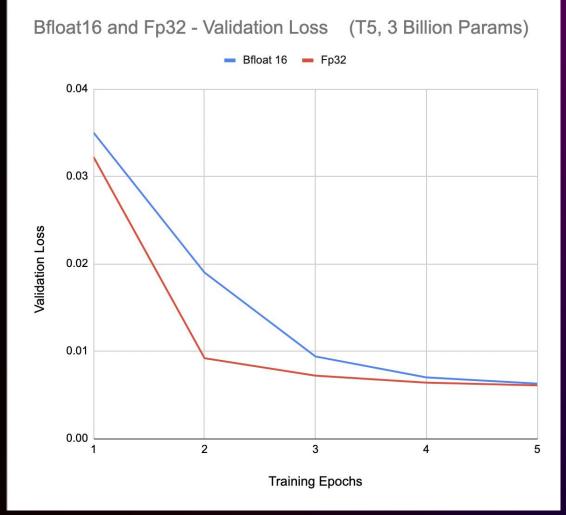
```
from torch.distributed.fsdp.fully_sharded_data_parallel import (
    FullyShardedDataParallel as FSDP,
   CPUOffload,
   BackwardPrefetch,
   MixedPrecision,
bf16 = MixedPrecision(
        # Param precision
        param dtype=torch.bfloat16,
        # Gradient communication precision.
        reduce dtype=torch.bfloat16,
model = FSDP(
       model,
       MixedPrecision=bf16, # bf16, fp16
```

BF16 is only available on Ampere GPUs. V100 may not complain but results in slowdowns.

Make sure if using FP 16 use ShardedGradScaler from FSDP

BFloat16 can deliver up to 4x training speed vs FP32





Transformer wrapping policy:

```
from torch.distributed.fsdp.wrap import (
    transformer auto wrap policy,
from transformers.models.t5.modeling_t5 import T5Block
transformer_auto_wrapper_policy = functools.partial(
        transformer auto wrap policy,
        transformer_layer_cls={
            T5Block, # < ---- Your Transformer layer class
        },
model = FSDP(
        model,
        auto_wrap_policy=transformer_auto_wrapper_policy,
```

```
Transformer Wrapping policy → more finegrained and balanced FSDP units.

Significantly improves communication efficiency.

2x throughput
```

alternative to:

increase

Activation Checkpointing:

```
# verify we have FSDP activation support ready by importing:
from torch.distributed.algorithms._checkpoint.checkpoint_wrapper import (
    checkpoint wrapper,
   CheckpointImpl,
   apply_activation_checkpointing_wrapper,
# first step - we have to make a check function to find what layers we want to checkpoint.
# For transformers, you'll want to use the same layers as you used for wrapping your transformer.
from transformers.models.t5.modeling_t5 import T5Block
# second create the submodule check function as a lambda:
check fn = lambda submodule: isinstance(submodule, T5Block)
# create a non-reentrant wrapper.
# This is basically to provide some options for the checkpoint wrapper,
# and we use non-reentrant style for best performance.
non_reentrant_wrapper = partial(
    checkpoint_wrapper,
   offload to cpu=False,
    checkpoint impl=CheckpointImpl.NO REENTRANT,
# Important - the next step is actually to init your model with FSDP.
# Activation checkpointing is shard aware, so it must be done ** after ** FSDP init:
model = FSDP (model)
# finally, we'll apply the checkpoint wrapper, and submodule check lamdba to your sharded model
# to complete the activation checkpointing process:
apply_activation_checkpointing_wrapper(
       model, checkpoint_wrapper_fn=non_reentrant_wrapper, check_fn=check_fn
```

Generally save 30% memory

Reinvest in batch size → ~7x throughput on DeepVit

FSDP Activation checkpointing is shard aware → use after FSDP init.

Backward Prefetch:

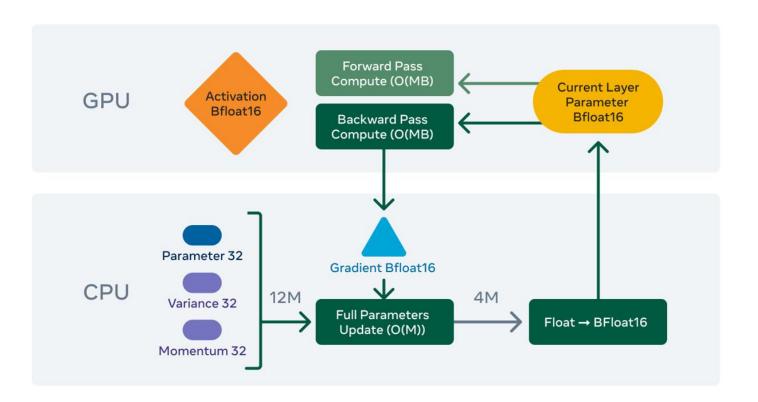
```
# import FSDP and BackwardPrefetch class
from torch.distributed.fsdp import (
    FullyShardedDataParallel as FSDP,
    BackwardPrefetch,
# None (i.e. don't pass anything) = summon for next FSDP unit comes after the all_reduce for current layer gradients
# BackwardPrefetch.BACKWARD_POST = prefetch at the end of current FSDP unit computation, after params are dropped
# BackwardPrefetch.BACKWARD_PRE = prefetch at start of current FSDP unit computation (earliest, adds to peak memory)
prefetch_policy = BackwardPrefetch.BACKWARD_PRE # BackwardPrefetch.BACKWARD_POST or None
model = FSDP(
        model,
        backward_prefetch=prefetch_policy,
```



CPU Offloading

Leverage CPU Memory to house 'non-active' parameters

Allows expansion beyond the total sum of GPU memory.



Saving your model - leverages CPU memory

```
if cfg.save model:
    # assembling model on rank0 and stream it to cpu to avoid 00M
    save_policy = FullStateDictConfig(offload_to_cpu=True, rank0_only=True)
    with FSDP.state_dict_type(
        model, StateDictType.FULL_STATE_DICT, save_policy
    ):
        cpu_state = model.state dict()
    if rank == 0:
        print(f"--> saving model ...")
        currEpoch = "-" + str(epoch) + "-train.pt"
        model save name = save name + currEpoch
        torch.save(cpu_state, model_save_name)
        print(f"--> saved {model_save_name} to disk")
```

Avoid OOMs on rank0 GPU

Leverage CPU memory

→ work for very

large models ~ 20B

Example of auto-wrapping (just print the model to view!)

```
model = t5-large, sharded with 2000000 parameters per fsdp_unit
 3
    --> t5-large has 737.668096 Million params
 5
    model wrapping =
    FullyShardedDataParallel(
       (_fsdp_wrapped_module): FlattenParamsWrapper(
 8
         (_fpw_module): T5ForConditionalGeneration(
           (shared): Embedding(32128, 1024)
10
           (encoder): T5Stack(
11
             (embed_tokens): Embedding(32128, 1024)
12
             (block): ModuleList(
13
               (0): T5Block(
14
                 (layer): ModuleList(
15
                   (0): T5LayerSelfAttention(
16
                     (SelfAttention): T5Attention(
17
                       (q): Linear(in_features=1024, out_features=1024, bias=False)
18
                       (k): Linear(in_features=1024, out_features=1024, bias=False)
19
                       (v): Linear(in_features=1024, out_features=1024, bias=False)
20
                       (o): Linear(in_features=1024, out_features=1024, bias=False)
21
```



PyTorch FSDP implementation:

Highlights of the major sub-sections:

```
# ---- main FSDP init -----
208
209
         model = FSDP(
210
             model,
             auto_wrap_policy=my_auto_wrap_policy,
211
             mixed_precision=mp_policy,
212
213
             backward_prefetch=prefetch_policy,
             device id=torch.cuda.current device(),
214
             sharding strategy=ShardingStrategy.FULL_SHARD, # Sharding options ...
215
216
                                                              # SHARD_GRAD_OP = Zero2,
217
                                                              # NO SHARD = DDP
             cpu_offload= cpu_policy,
218
             forward_prefetch=True,
219
220
221
222
         if cfg.fsdp_activation_checkpointing:
223
             fsdp_checkpointing(model)
224
             if local_rank==0:
225
                 print(f"--> FSDP activation checkpointing in use")
226
```

Some Best practices:

- 1 BFloat16 increases training speed, 35% to 4x...and 32% memory reduction.
- 2 Backward pre fetch via BACKWARD_PRE ... 2 10% training speedup.
- 3 Use the rank_0 cpu saving to avoid any OOM issues during large model saving.
- 4 Use activation checkpointing this frees up large amounts of memory during training.
- 5 Proper wrapping For Transfomers use Transfomer wrapping policy

AnyPrecision Optimizer - run FSDP in pure BF16

Q - Why only mixed precision? Why not 100% BF16?

A - Pure BF16 doesn't work...

Problem = weight stagnation due to small updates being lost

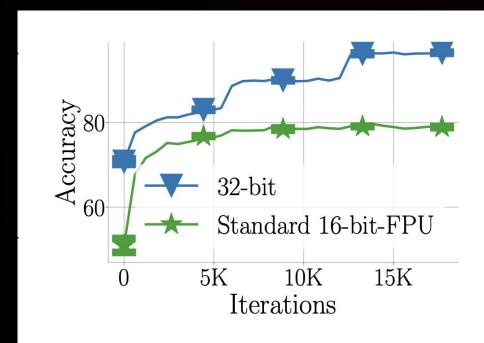


Figure 1: Standard 16-bit-FPU training shows lower training accuracy compared to 32-bit training on a BERT model.²

Paper - https://arxiv.org/abs/2010.06192 (Revisiting BFloat16 training)

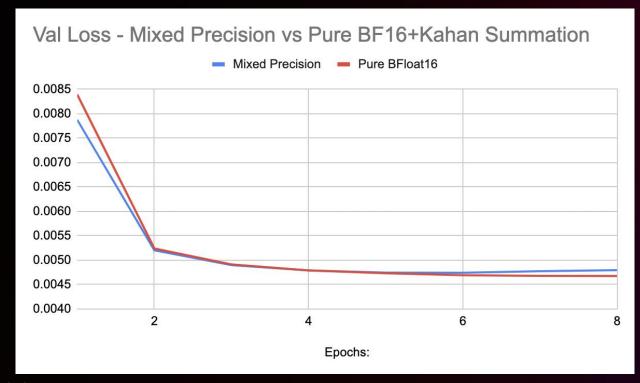


AnyPrecision Optimizer - run FSDP in pure BF16

Solution - AnyPrecision uses Kahan summation in the optimizer for weight updates.

Significant memory, speed improvements with pure BF16, while matching or exceeding FP32. (~ 48% GPU memory reductions in initial testing vs FP32).

Drop in replacement for AdamW



Available in Torchdistx

https://github.com/pytorch/torchdistx



Working with extremely large models

PyTorch has added several features to allow for instantiating models without having to load the actual weights.

This allows extremely large models (think 175B+ that would OOM on CPU) to be loaded, inspected and ultimately sharded as only the shapes, not the weights, are loaded.

This includes:

Meta device

Deferred initialization

Fake Tensor



META DEVICE

Instantiate Module/ tensor onto a meta device

It has tensor shape, does not allocate any storage

```
# 1. Initialize module on the meta device; all torch.nn.init ops have
# no-op behavior on the meta device.
m = nn.Linear(10, 5, device='meta')

# 2. Materialize an uninitialized (empty) form of the module on the CPU device.
# The result of this is a module instance with uninitialized parameters.
m.to_empty(device='cpu')

meta_tensor = torch.randn(100000, 100000, device="meta")
```

https://pytorch.org/tutorials/prototype/skip_param_init.html#implementation-details



Deferred initialization

Deferred module init has

deferred_init() ,
materialize_module()
,
materialize_tensor().

deferred_init() , construct model without allocating storage for their tensors

materilize_module(), materialize_tensor(), fully or partially materialize modules.

```
import torch
from torchdistx.deferred init import deferred init, materialize module
class MyModule(torch.nn.Module):
    def init (self):
        super().__init__()
        self.param = torch.nn.Parameter(torch.ones([3], device="cpu"))
m = deferred_init(MyModule):
m.param
#Parameter containing:
#tensor(..., device='cpu', size=(10, 10), requires grad=True, fake=True)
materialize_module(m)
m.param
#Parameter containing:
#tensor([1., 1., 1.], requires grad=True)
```

Available in Torchdistx https://github.com/pytorch/torchdistx



Fake Tensor

Similar to meta_tensors, does not contain any data

Fake tensors act as if allocated to a real device

It has been meant mostly to use a building block for deferred module init.

It can be useful to load the model without initializaing it with data.

Available in Torchdistx

```
import torch
                             from torchdistx.fake import fake mode
                            # Meta tensors are always "allocated" on the `meta` device.
                             a = torch.ones([10], device="meta")
                            #tensor(..., device='meta', size(10,))
                            a.device
                            #device(type='meta')
                            # Fake tensors are always "allocated" on the specified device.
                            with fake mode():
                                 b = torch.ones([10])
                            #tensor(..., size(10,), fake=True)
                            b.device
                                                     import torch
                            #device(type='cpu')
                                                     from transformers import BlenderbotModel, BlenderbotConfig
                                                     from torchdistx.fake import fake_mode
                                                     # Instantiate Blenderbot on a personal laptop with 8GB RAM.
                                                     with fake mode():
                                                         m = BlenderbotModel(BlenderbotConfig())
                                                     # Check out the model layers and their parameters.
https://github.com/pytorch/torchdistx
                                                     #BlenderbotModel(...)
https://pytorch.org/torchdistx/latest/fake_tensor.htm.
```



Fake Tensor

Meta device work great for skipping initialization

It might not work in all case for materilization when working in deferred initialization context.

some of pytorch functions like zero_like, refers to src.device

Fake tensor can solve this issue.

```
class MyModule(Module):
     def init (self):
         super().__init__()
         self.buf1 = torch.ones([3], device="cpu")
         self.buf2 = torch.zeros_like(self.buf1)
my_module = deferred_init(MyModule)
materialize tensor(my module.buf1)
#tensor([1., 1., 1.])
materialize_tensor(my_module.buf2)
#tensor(..., device='meta')
```

Available in Torchdistx

https://github.com/pytorch/torchdistx

https://pytorch.org/torchdistx/latest/fake_tensor.html

_https://pytorch.org/torchdistx/latest/fake_tensor_and_deferred_init.html



TorchSnapshot

Torchsnapshot offers highly optimized checkpointing ~2x faster than save()

5x faster than saving a GPU on S3 compared to save()+fsspec

Adaptive to the host memory – avoid OOMs during checkpointing

Can save/load GPU model using temporary memory a fraction of the size of largest tensor in the model

Load 20GB from storage to GPU with 100MB temp memory

Supports S3, GCS

Available in Torchsnapshot

aws

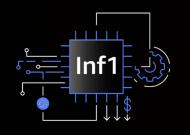
https://pytorch.org/torchsnapshot/

```
app_state = {"model": model, "optimizer": optimizer}
from torchsnapshot import StateDict
extra_state = StateDict(iterations=0)
app_state = {"model": model, "optimizer": optimizer, "extra_state": extra_state}
from torchsnapshot import Snapshot
snapshot = Snapshot.take(path="/path/to/my/snapshot", app_state=app_state)
snapshot.restore(app_state=app_state)
```

Inference at scale



Amazon EC2 accelerated compute for ML inference



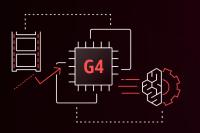
Inf1: Custom ML acceleration

- Low cost per inference in the cloud
- Up to 2,000 TOPs with AWS-designed Inferentia accelerators
- Designed for high throughput and low latency



G5: GPU compute instance

- 3–4x ML inference performance compared to previous generations
- 8x NVIDIA A10G 24 GB, 100 Gb/s

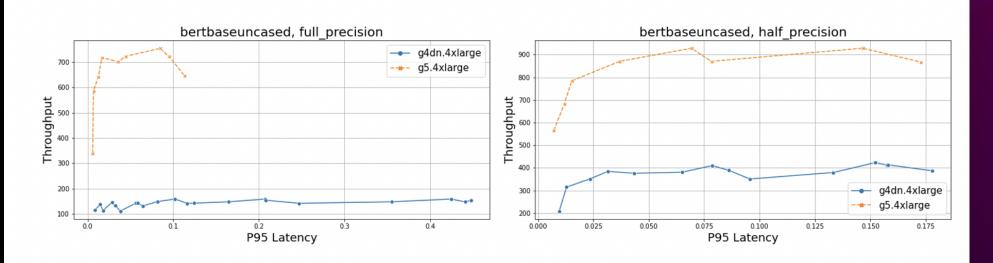


G4dn: GPU compute instance

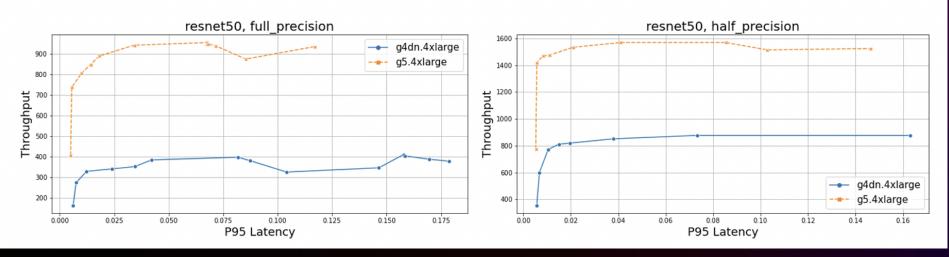
- Up to 1,030 TOPs of compute with 8x NVIDIA T4 GPUs
- Low-cost GPU-based instances



G5 vs. G4dn

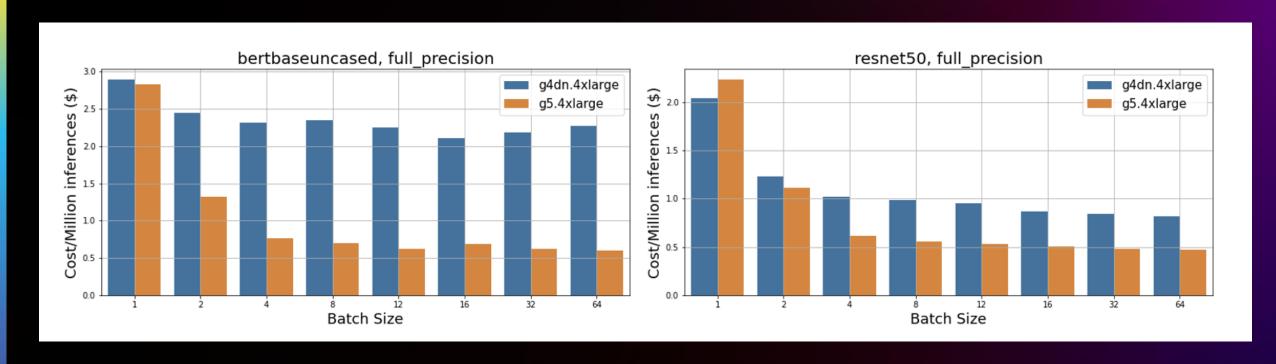


The following graphs compare throughput and P95 latency at full and half precision for ResNet50.





Cost performance

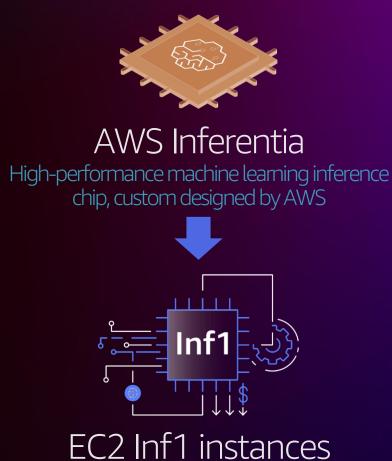


With G5 instances, you can achieve consistently lower cost-per-inference compared to G4dn instances

Amazon EC2 Inf1 instances

HIGH-PERFORMANCE, LOW-COST MACHINE LEARNING INFERENCE

- Featuring AWS Inferentia, the first ML chip designed by Amazon
- Low cost in the cloud for running deep-learning models, up to 70% lower cost than GPU instances
- Up to 2.3x higher throughput than GPU-based instances
- Seamless software integration with ML frameworks like TensorFlow, PyTorch, and MXNet for getting started quickly and with minimal code changes
- Get started using DLC, DL AMIs, Amazon EKS, Amazon ECS, or Amazon SageMaker



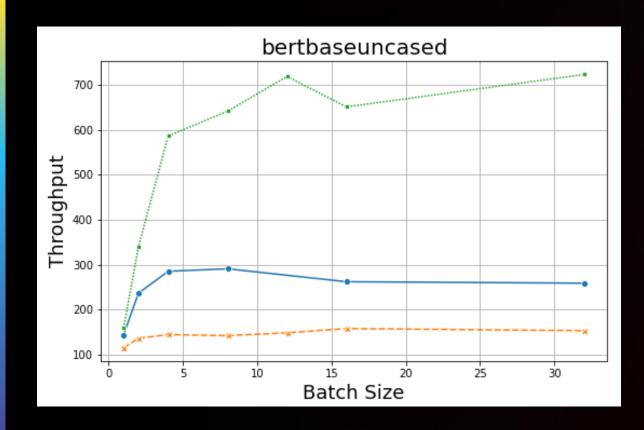
Fast and low-cost inference in the cloud

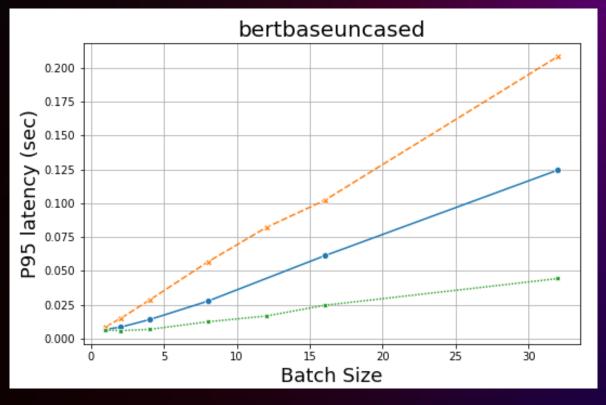


Inf1 vs. G5 and G4dn

NATURAL LANGUAGE PROCESSING

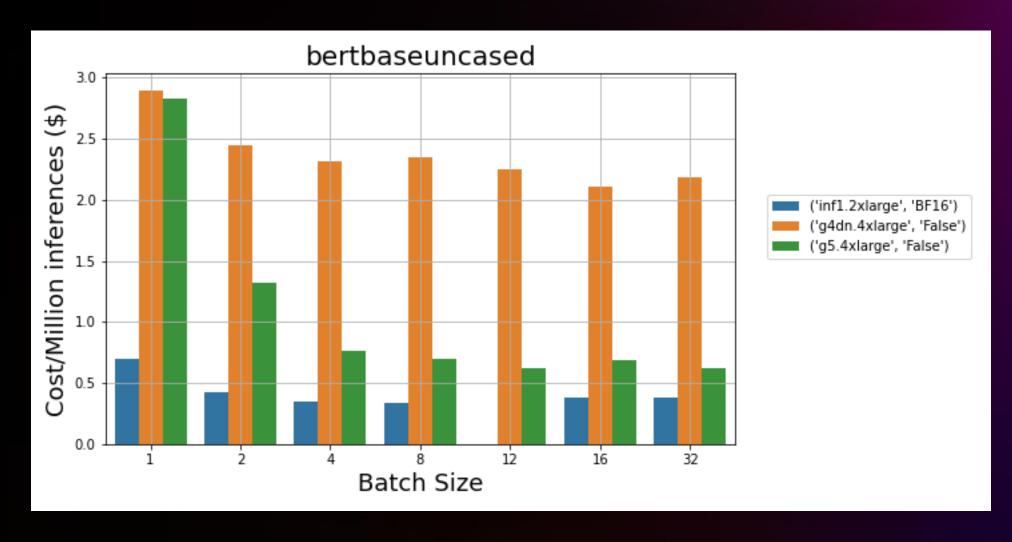
G5.4xlarge Inf1.2xlarge G4dn.4xlarge





NATURAL LANGUAGE PROCESSING

G5.4xlarge Inf1.2xlarge G4dn.4xlarge

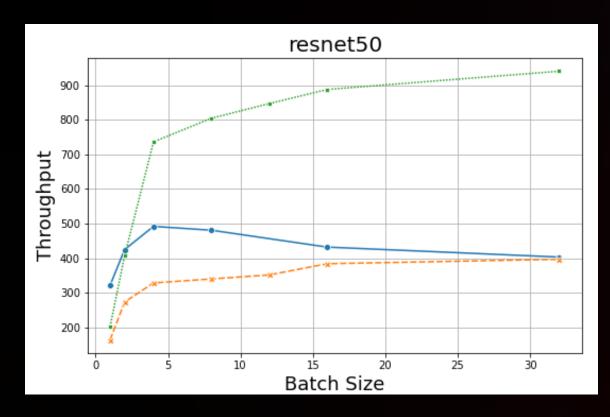


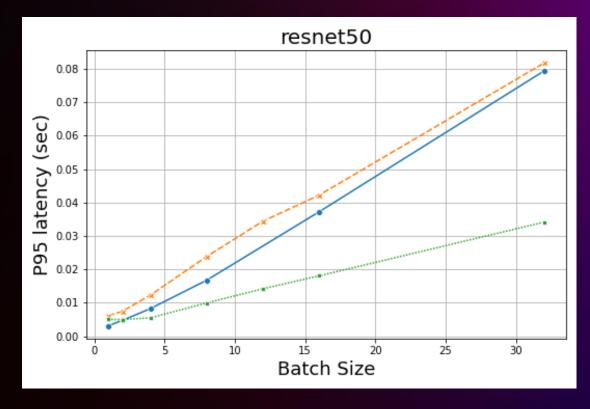


Inf1 vs. G5 and G4dn

COMPUTER VISION

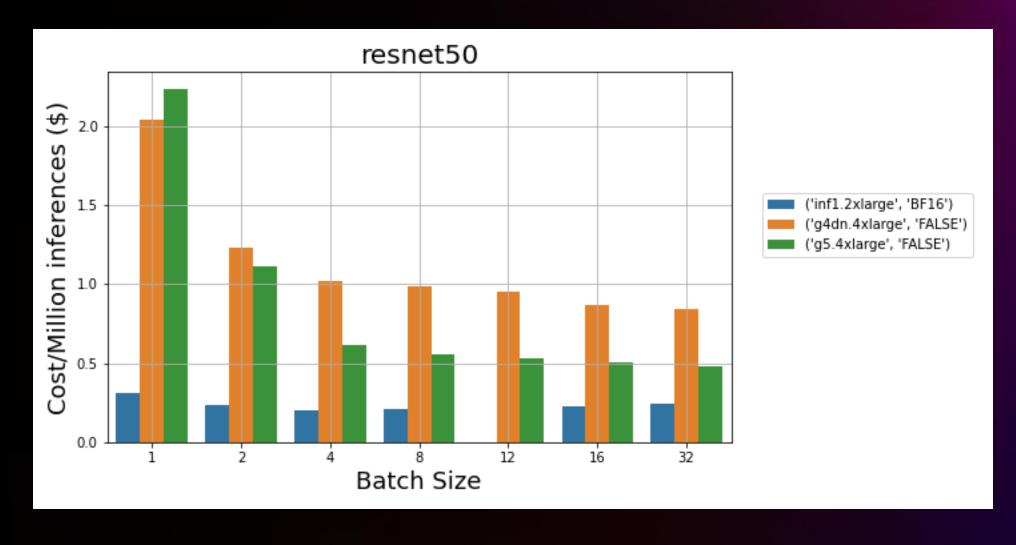






G5.4xlarge Inf1.2xlarge G4dn.4xlarge

COMPUTER VISION





Proof of concept

BRINGING THE CREATIVE POTENTIAL OF AI TO EVERYONE

Startup requirements:

Build personalized creative AI models for mentorship, AMA, interactive NFTs, and more

9–10 models per user

Mostly NLP models

G4dn instances

Need to load, unload, and infer models in parallel

Challenges:

Low GPU utilization

High cost

High latency due to big models

Proposed a solution with AWS Inferentia and FastAPI

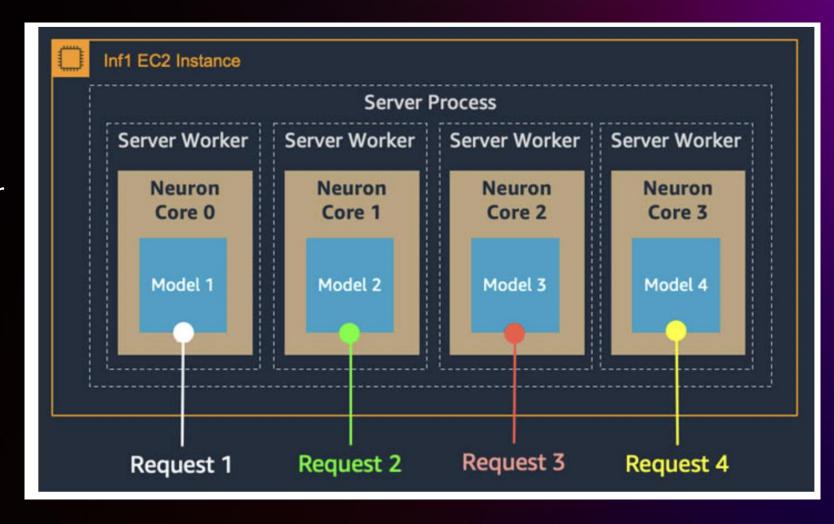
Impact:

Customer is satisfied with the approach, considering implementing in production



Loading models in parallel

- One python process can be tied to one Neuron Core with NEURON_RT_VISIBLE_CORES environment variable.
- This allows one model server per user or a set of users on one Neuron Core.
- With this approach, we can load, unload and infer models in parallel while maintaining high utilization of all 4 cores on an AWS Inferentia chip.





Amazon EKS



aws-do-eks framework

Use aws-do-eks framework (https://github.com/aws-samples/aws-do-eks)

Set up desired cluster using a conf file

Creates a docker container with all the tools needed to mange the cluster

Automatically sets up necessary IAM roles, VPC, security groups, autoscaling groups, etc.

Provides various tools for setting up persistent volumes, GPU monitoring, launching model training jobs, etc.



How to set up an Amazon EKS cluster

Walkthrough config

Steps:

Fill out config

Build and run in a container

eks-create.sh: Create auto scaling groups

eks-scale.sh: Scale nodes to desired capacity

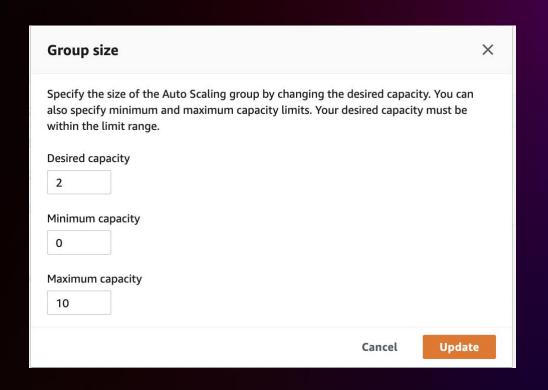
IAM roles are created for each node group but additional roles, like access to Amazon S3 or Amazon CloudWatch, may need to be added

Spot Instances

Custom AMIs

After a cluster is created:

- New nodegroups can be added after a cluster is created with eks-nodegroup-create.sh
- Nodegroups can be scaled via eks-scale.sh or via console.





Shared file system

- Need a shared file system that all nodes in the cluster can access
- File system should be elastic and performant for large data



Amazon Elastic File System (EFS)

- efs-create.sh Creates security group and a new Amazon EFS volume
- deploy.sh
 - Gets existing file system ID
 - Deploys Amazon EFS CSI driver
 - If multiple volumes exist, takes the first one given by aws efs describe-file-systems
 - Deploys file system on Amazon EKS



Amazon FSx for Lustre

- Can be deployed to 1 AZ
- Update fsx.conf file
- Run deploy.sh This will create the security group that you need for FSx and also create the storage class
- Create the FSx filesystem from AWS console
- Update fsx-pvc-static.yaml with the information from FSx console
- Kubectl apply fsx-pvc-static.yaml.

https://github.com/aws-samples/aws-do-eks/tree/main/Container-Root/eks/deployment/csi



Serve 3,000 deep-learning models on Amazon EKS with AWS Inferentia for under \$50 an hour

Exp. #	Instances (num x type)	Models (num)	Sequential Response (ms)	Random Response (ms)	Throughput (req/s)	Latency with Load P90 (ms)	On-Demand Cost (\$/hr)
#							
1	3 x inf1.6xl	144	21 – 32	21 – 30	142	57	3.54
2	5 x inf1.6xl	240	23 – 35	21 – 35	173	56	5.9
3	21 x inf1.6xl	1008	23 – 39	23 – 35	218	24	24.78
4	32 x inf1.6xl	1536	26 – 33	25 – 37	217	23	37.76
5	4 x g4dn.12xl	288	27 – 34	28 – 37	178	30	15.64
6	14 x	1000	26 75	74 44	454	7.0	E 4.70
	g4dn.12xl	1008	26 – 35	31 – 41	154	30	54.76
	32 x inf1.6xl +						
7	21 x	3048	27 – 35	24 – 45	248	28	119.91
	g4dn.12xl						
8	40 x inf1.6xl	3002	24 – 31	25 – 38	1536	33	47.2
	40 x inf1.6xl						
9	(With DNS	3040	24 – 31	25 – 38	6230	66	47.2
	Caching)						



Setting up for success at AWS

Mission: Meet customers where they are, help them adopt and scale ML workloads on AWS with Amazon EC2, key services, and open-source tools and frameworks (PyTorch, TensorFlow)

Architecting scalable solutions

using Amazon EC2, Amazon EKS, Amazon ECS, AWS Batch, Spot, KubeFlow, Ray, PyTorch, TensorFlow, etc.

EC2 instance selection

via benchmarking for specific models and workloads (e.g., P4d for training, G4dn, G5, Inf1 for inference).

Develop proofof-concepts

to show the art of the possible, unblock technical challenges, and advise on best practices. Proof of concept credits available.

Guidance on **PyTorch**

adoption, scaling, roadmap dives deep in threeway discussions with Meta (if needed).

Areas of interest: NLP, CV, distributed training, ML inference, MLOPs

"Meta and AWS will jointly help enterprises use PyTorch on AWS to bring deep learning models from research into production faster and easier." Meta/AWS Press Release, December 2021



Thank you!

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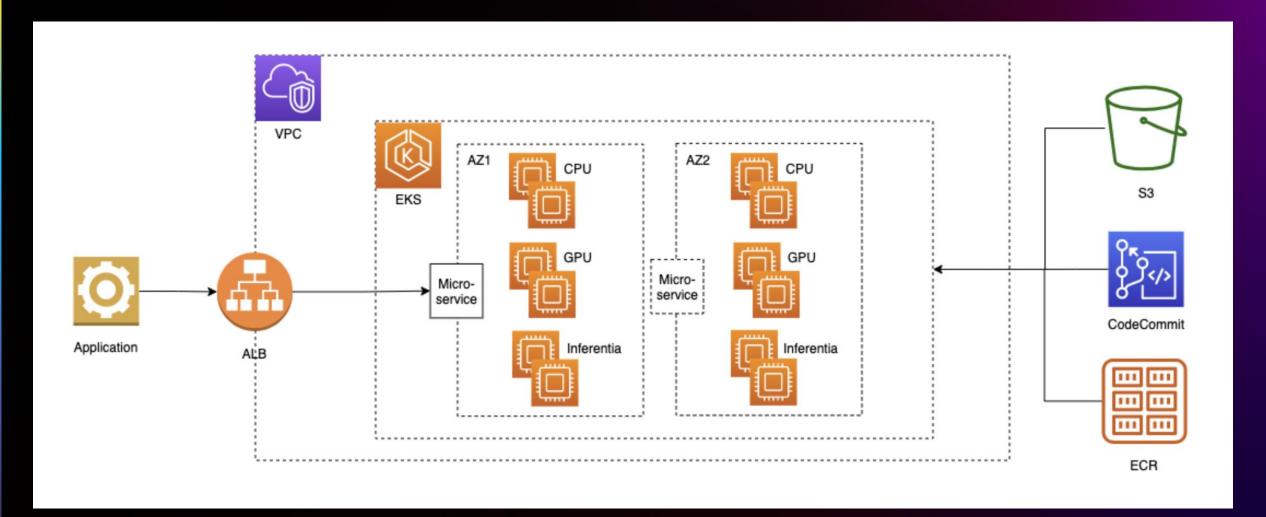
@ankur_rice



Please complete the session survey in the **mobile app**



Architecture



Moving data from Amazon S3 to Amazon EFS

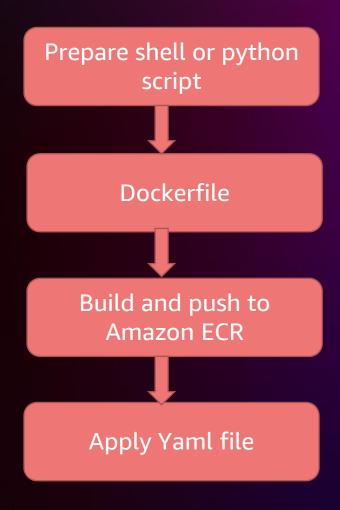
Once a cluster and a file system is created, you might need to:

Move compressed data from Amazon S3 to Amazon EFS

Uncompress data in Amazon EFS

Preprocess data with shell scripts

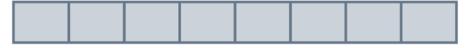
Or, preprocess data with python code



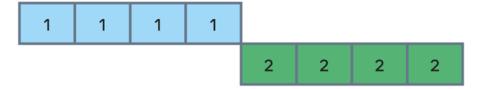


FSDP Deep Dive: parameter level

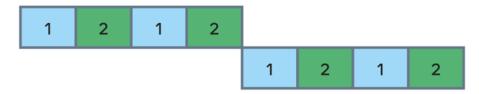
Flattened params from model - 8 total



Typical ownership



Sharding strategy = FSDP Unit of 4 params, with sequential shard ownership by ranks (GPU)

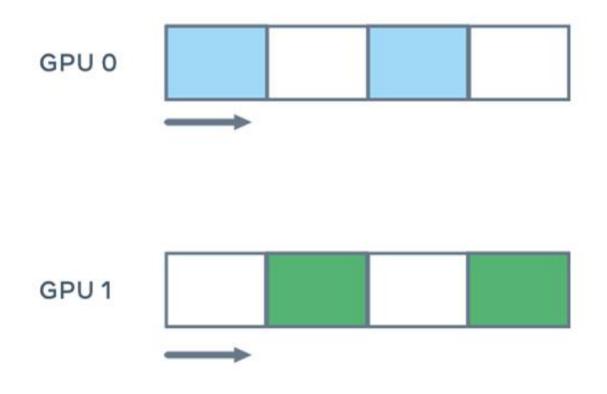




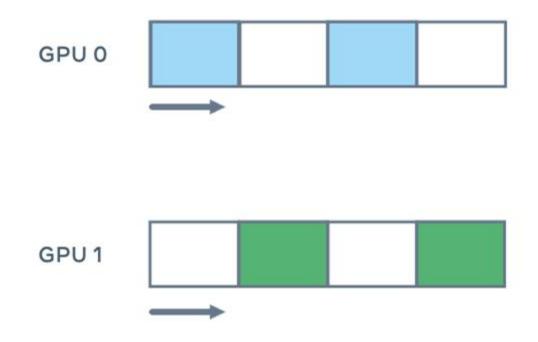
Flattened params from model - 8 total



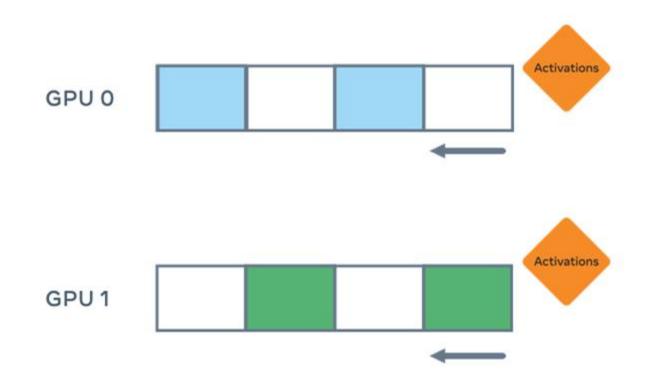
Forward pass on first FSDP Unit. Begin All-Gather.



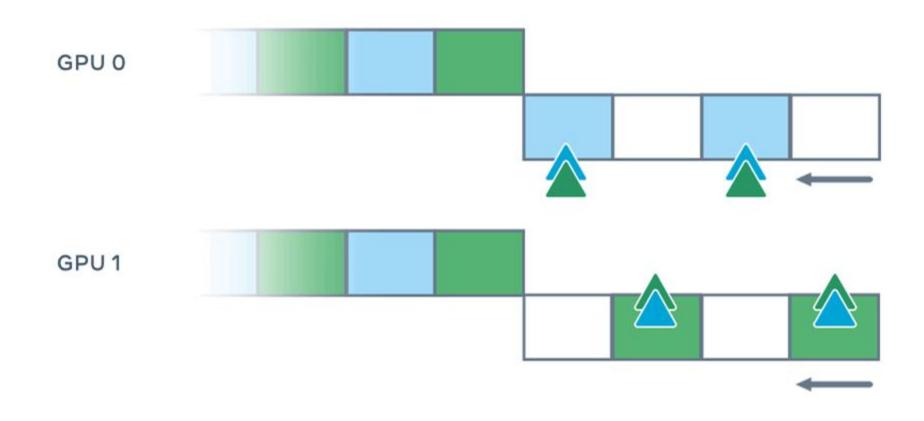
Non locally owned params are dropped to free memory. Activations (orange) can be checkpointed. Forward pass continues until we complete model.



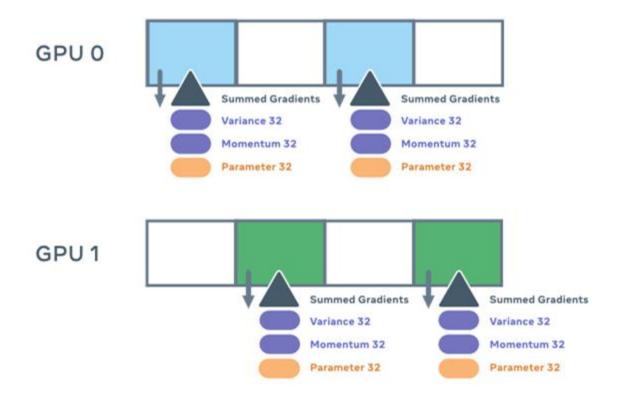
Backward Pass: another All-Gather, compute gradients.



Reduce and aggregate gradients.



Run new gradient in optimizer step.
Update params (FP32 Master Params).
Repeat entire cycle until training is complete.



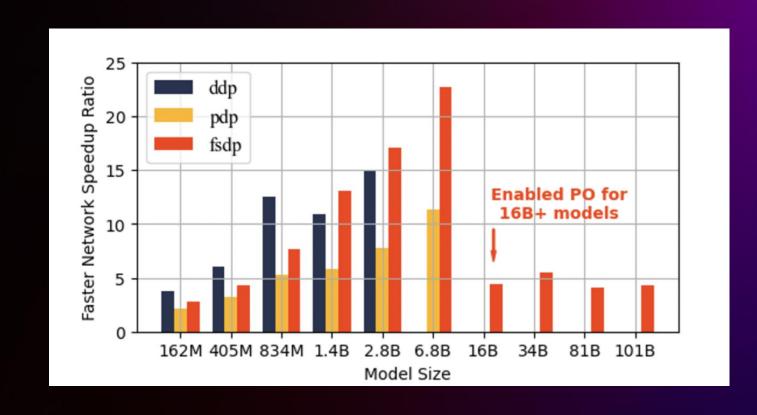
FSDP - network communication speed is very important

FSDP interleaves communication with computation.

Thus, as communication speed increases, FSDP accelerates.

The Just in Time delivery of parameters in FSDP allows huge model scaling.

EFA on AWS enables higher speed (400BG/S)



https://medium.com/pytorch/pytorch-data-parallel-best-practices-on-google-cloud-6c8da2be180d



Integrations

FSDP is integrated into HuggingFace



FSDP is integrated into Lightnining



TorchSnapshot

Highly optimized performance from

- Overlapped DtoH copy and storage I/O
- Highly parallelized storage I/O
- 0 copy tensor serialization
- (For data parallel only) evenly partitioning the write workload across all ranks

Our initial benchmark shows

- 2x faster than torch.save when saving GPU model to local FS
- 5x faster than torch.save + fsspec + s3fs when saving GPU model to S3
- For data parallel workload, up to[NUM_DEVICES]x additional speed up

```
app_state = {"model": model, "optimizer": optimizer}

from torchsnapshot import StateDict

extra_state = StateDict(iterations=0)
app_state = {"model": model, "optimizer": optimizer, "extra_state": extra_state}

from torchsnapshot import Snapshot

snapshot = Snapshot.take(path="/path/to/my/snapshot", app_state=app_state)

snapshot.restore(app_state=app_state)
```





TorchSnapshot

Memory usage

- Removes the hard RAM requirement for saving/loading checkpoints. RAM usage is adaptive to available system resource and bound, which greatly reduces the chance of running out of RAM
- When RAM is abundant, TorchSnapshot can further reduce the time spent blocking in checkpoint saving by staging the model weights in RAM and flush the weights to storage in background once training resumes

```
app_state = {"model": model, "optimizer": optimizer}

from torchsnapshot import StateDict

extra_state = StateDict(iterations=0)
app_state = {"model": model, "optimizer": optimizer, "extra_state": extra_state}

from torchsnapshot import Snapshot

snapshot = Snapshot.take(path="/path/to/my/snapshot", app_state=app_state)

snapshot.restore(app_state=app_state)
```

Efficient checkpoint content access

- Only read from storage what is needed aws (e.g. reading a tensor from a checkpoint) Available in Torchsnapshot https://pytorch.org/torchsnapshot/

DEBUGING DISTRIBUTED TRAINING

DEBUGGING DISTRIBUTED TRAINING



Monitored Barrier

- Alternative primitive to torch.distributed.barrier()
- Mainly meant for debugging
- Option to set a custom timeout
- Rank 0 reports which rank did not enter the barrier within given timeout
- All worker fail if one rank is missing
- Only available for GLOO backend

```
import os
from datetime import timedelta

import torch
import torch.distributed as dist
import torch.multiprocessing as mp

def worker(rank):
    dist.init_process_group("nccl", rank=rank, world_size=2)
    # monitored barrier requires gloo process group to perform host-side sync.
    group_gloo = dist.new_group(backend="gloo")
    if rank not in [1]:
        dist.monitored_barrier(group=group_gloo, timeout=timedelta(seconds=2))

if __name__ == "__main__":
    os.environ["MASTER_ADDR"] = "localhost"
    os.environ["MASTER_PORT"] = "29501"
    mp.spawn(worker, nprocs=2, args=())
```

```
RuntimeError: Rank 1 failed to pass monitoredBarrier in 2000 ms Original exception:
[gloo/transport/tcp/pair.cc:598] Connection closed by peer [2401:db00:eef0:1100:3560:0:1c05:25d]:8594
```



Torch_DISTRIBUTED_DEBUG

- Enables additional debugging information
- Two levels of detail
- INFO level
 - Prints info after initialization only
 - Enhanced crash logging due to unused parameter in model
- DETAIL
 - Print timing info during iterations
 - Has impact on training efficiency
 - Additional checks of synchronization and input of collective functions
 - Combine with
 TORCH_SHOW_CPP_STACKTRACES=
 1 for full callstacks on

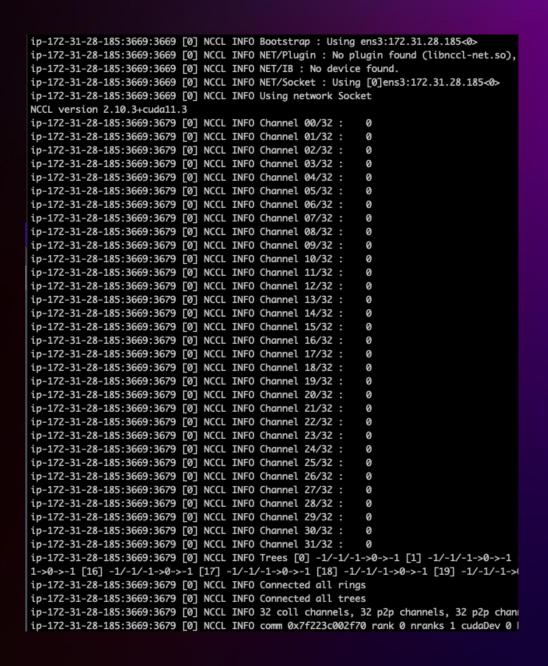
```
I0607 16:10:35.739390 515217 logger.cpp:173] [Rank 0]: DDP Initialized with:
broadcast_buffers: 1
bucket_cap_bytes: 26214400
find_unused_parameters: 0
gradient_as_bucket_view: 0
is_multi_device_module: 0
iteration: 0
num_parameter_tensors: 2
output device: 0
rank: 0
total_parameter_size_bytes: 440
world_size: 2
backend_name: nccl
bucket_sizes: 440
cuda_visible_devices: N/A
device_ids: 0
dtvpes: float
master_addr: localhost
master_port: 29501
module_name: TwoLinLayerNet
nccl_async_error_handling: N/A
nccl_blocking_wait: N/A
nccl_debug: WARN
nccl_ib_timeout: N/A
nccl_nthreads: N/A
nccl_socket_ifname: N/A
torch distributed_debug: INFO
```

```
I0607 16:18:58.085693 544066 logger.cpp:344] [Rank 0 / 2] Training TwoLinLayerNet unused_parameter_size=0
Avg forward compute time: 42850427
Avg backward compute time: 3885553
Avg backward comm. time: 2357981
Avg backward comm/comp overlap time: 2234674
```



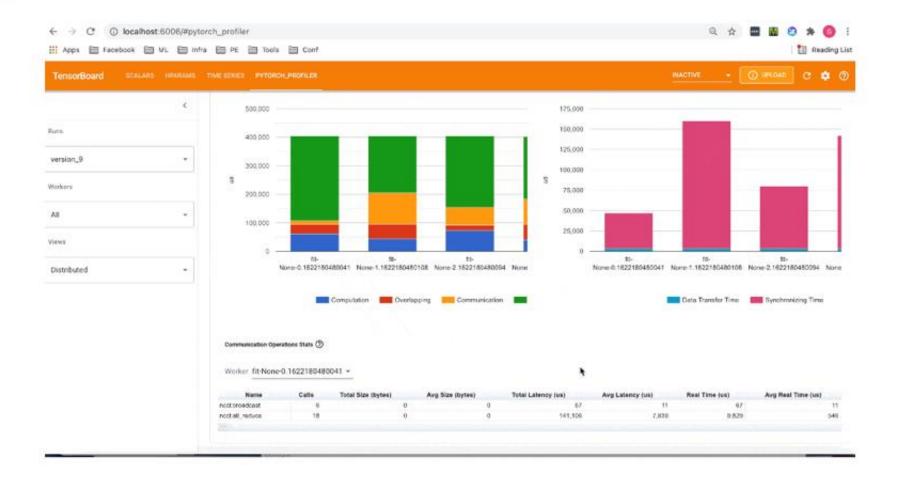
NCCL_DEBUG

- Set NCCL_DEBUG for additional debug information
- VERSION
 - Just print the version at startup
- WARN
 - Lets NCCL print more explicit messages in case of an error
- INFO
 - Highest level
 - Prints excessive debug information
 - Comm channel availability
 - Ring setup
 - Un-/Normal termination



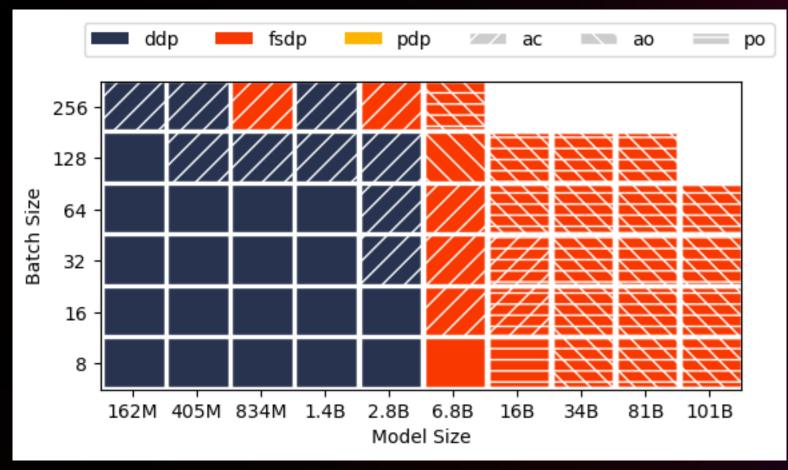
Pytorch Profiler





Where does FSDP fit in (vs DDP)

Model scale and recommendations are network speed dependent: With NVLink, 100M+ = FSDP! (universal training)





Speedup over G4dn

Model	Batch size	Precision	Throughput (batch size X requests/sec)		Latenc	Latency (ms)		n es (on demand)	Cost benefit (G5 over G4dn)
			G5	G4dn	G5	G4dn	G5	G4dn	
	72	Full	723	154	44	208	\$0.6	\$2.2	3.7X
	32	Mixed	870	410	37	79	\$0.5	\$0.8	1.6X
Dout have unessed	16	Full	651	158	25	102	\$0.7	\$2.1	3.0X
Bert-base-uncased	16	Mixed	762	376	21	43	\$0.6	\$0.9	1.5X
	0	Full	642	142	13	57	\$0.7	\$2.3	3.3X
	8	Mixed	681	350	12	23	\$0.7	\$1.0	1.4X
	1	Full	160	116	6	9	\$2.8	\$2.9	1.0X
		Mixed	137	102	7	10	\$3.3	\$3.3	1.0X
		Full	941	397	34	82	\$0.5	\$0.8	1.6X
	32	Mixed	1533	851	21	38	\$0.3	\$0.4	1.3X
		Full	888	384	18	42	\$0.5	\$0.9	1.8X
ResNet50	16	Mixed	1474	819	11	20	\$0.3	\$0.4	1.3X
		Full	805	340	10	24	\$0.6	\$1.0	1.7X
	8	Mixed	1419	772	6	10	\$0.3	\$0.4	1.3X
	1	Full	202	164	5	6	\$2.2	\$2	0.9X
		Mixed	196	180	5	6	\$2.3	\$1.9	0.8X



Amazon EC2 G5 instances

Using NVIDIA A10G GPU with 24GB GPU memory

- 3–4x higher graphics and ML performance
- 80 2nd-gen RT cores

AMD Rome CPUs

Up to 3.3GHz core frequency



Instance size	GPU	vCPU	Memory (GB)	GPU memory (GB)	Storage (GB)	Network bandwidth (Gb/s)	EBS bandwidth (Gb/s)
G5.xlarge	1	4	16	24	250	Up to 10	Up to 3.5
G5.2xlarge	1	8	32	24	450	Up to 10	Up to 3.5
G5.4xlarge	1	16	64	24	600	Up to 25	8
G5.8xlarge	1	32	128	24	900	25	16
G5.16xlarge	1	64	256	24	1900	25	16
G5.12xlarge	4	48	192	96	3800	40	16
G5.24xlarge	4	96	384	96	3800	50	19
G5.48xlarge	8	192	768	192	7600	100	19



Technical details

- AWS Inferentia is 45% cheaper than g4dn instances and can achieve 3.5 times the throughput for large NLP models.
- Compiled models have 5–6 times smaller memory footprint.
- Benchmarked throughput of models while loading and unloading in parallel on a GPU, low GPU utilization because load and unload API calls given preference than inference API.
- Similar default behavior with AWS Inferentia Neuron Cores; models get loaded sequentially on Neuron Cores.

